
k3math

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k3math is a toy math impl

- *Documentation for the Code*
 - *Classes*

DOCUMENTATION FOR THE CODE

1.1 Classes

class `k3math.Vector (*args, **kwargs)`

A Vector is a list supporting operations:

- `+`: vector adds vector
- `-`: vector subtracts vector
- `*`: vector times scalar
- `**`: vector powers scalar

inner_product (*b*)

Calculate inner product of two vector and returns a new Vector.

class `k3math.Matrix (vectors)`

determinant ()

Calculate determinant of this matrix. E.g.:

$$\begin{vmatrix} a & b \\ c & d \end{vmatrix} = a*d - b*c$$

Returns float

minor (*i, j*)

Make a new matrix without i-th row and j-th column.

solve (*ys*)

Solve equations:

$$\begin{vmatrix} a_{00} & a_{01} & a_{02} \\ a_{10} & a_{11} & a_{12} \\ a_{20} & a_{21} & a_{22} \end{vmatrix} * \begin{vmatrix} x_0 \\ x_1 \\ x_2 \end{vmatrix} = \begin{vmatrix} y_0 \\ y_1 \\ y_2 \end{vmatrix}$$

Parameters *y* (`Vector`) – a vector of *y0*, *y1*, *y2*.

Returns `Vector`

class `k3math.Polynomial (iterable=(, /))`

It represents a polynomial: $y = a_0 + a_1 * x^1 + a_2 * x^2 \dots$ Where *coefficients* = [*a0*, *a1*, *a2* ..].

xs and *ys* is array of x-coordinate value and y-coordinate value. They are all real numbers.

$$\mathbf{x}_S = [1, 2, 3, 4, 5..] \quad \mathbf{y}_S = [1, 2, 4, 7, 11..]$$

With xs and ys to calc the coefficients of a polinomial

degree is the highest power of polynomial: degree=2: $y = a_0 + a_1 \cdot x + a_2 \cdot x^2$

```
classmethod fit (xs, ys, degree)
```

Find a polynomial curve with least squares method.

Parameters

- **x** (`Vector`) – Vector of x positions
- **y** (`Vector`) – Vector of y positions
- **degree** (`int`) – the highest power of variable x in the polynomial.

Returns Polynomial

```
classmethod get_fitting_equation(xs, ys, degree)
```

Curve fit with least squares

We looking for a curve:

$$Y = a_0 + a_1 * x + a_2 * x^2$$

that minimize variance:

$$E = \text{sum}((Y[i]-y_s[i])^2)$$

Partial derivatives about $a_0..a_n$ are:

$$E'a_0 = \text{sum}(2 * (a_0 + a_1 * x_s[i] + a_2 * x_s[i]^2 - y_s[i]) * 1) \quad E'a_1 = \text{sum}(2 * (a_0 + a_1 * x_s[i] + a_2 * x_s[i]^2 - y_s[i]) * x_s[i]) \quad E'a_2 = \text{sum}(2 * (a_0 + a_1 * x_s[i] + a_2 * x_s[i]^2 - y_s[i]) * x_s[i]^2)$$

The best fit is a curve that minimizes E: or all partial derivatives are 0:

```

c00 c01 c02 || a0 || Y0 |
c10 c11 c12 | * | a1 | = | Y1 |
c20 c21 c22 || a2 || Y2 |

c00 = 2 * n c01 = 2 * sum(xs[i]) c02 = 2 * sum(xs[i]^2) Y0 = 2 * sum(ys[i])
c10 = 2 * sum(xs[i]) c11 = 2 * sum(xs[i]^2) c12 = 2 * sum(xs[i]^3) Y1 = 2 * sum(ys[i]*xs[i])
...

```

```
classmethod interpolation(xs, ys, degree, x)
```

guess value at x with polynomial regression

```
classmethod plot (polynomials, rangex, rangey=None, width=120, height=20, points=())
```

Plot a polynomial with text:

```
poly = [3.5, 3.4, 1]

for l in Polynomial.plot([(poly, '.')] ,
                          rangex=[-1, 6],
                          width=40, height=10):
    print l

#
#
#
#
#
#
#
```

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```
#
#
#
#
#
```

Parameters

- **polynomials** – list of a vector of polynomial coefficients and symbol:

```
[ ([1, 6], 'x'),      # y = 1 + 6x, plot with "x"
  ([2, 2, 2], '.'),  # y = 2 + 2x + 2x^2, plot with "."
]
```

- **rangex** (*float*) – is a tuple of two floats that specifies range of x.
- **rangey** (*float*) – is a tuple of two floats that specifies range of y.
- **width** (*int*) – specifies plot graph width.
- **height** (*int*) – specifies plot graph height.
- **points** – other points to add to the plot. It is a vector of (*x*, *y* [, *char*]). *char* is optional to specify point mark. By default it is X.

Returns list of strings

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